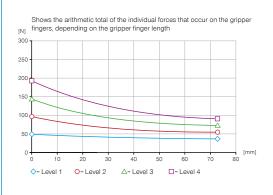
2-JAW PARALLEL GRIPPERS LWR50L-03-00002-A

PRODUCT SPECIFICATIONS

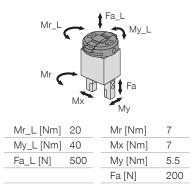


Gripping force diagram

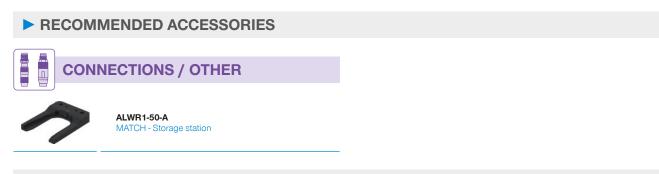


Forces and moments

Shows static forces and moments



| | Technical data |
|--|-------------------|
| Order no. | LWR50L-03-00002-A |
| General data | |
| MRK design according to ISO/TS 15066 | Yes |
| Control | I/O |
| Operating temperature [°C] | 5 +50 |
| Protection to IEC 60529 | IP40 |
| Weight [kg] | 0.76 |
| Tool changer specific data | |
| Electrical energy transfer | integrated |
| Locking stroke [mm] | 1 |
| Repetition accuracy in X, Y [mm] | 0.05 |
| Repetition accuracy in Z [mm] | 0.05 |
| Tightening force [N] | 50 |
| Release force [N] | 0 |
| Offset at coupling max. in X,Y [mm] | 1.0 |
| Gripper specific data | |
| Suitable for series | LWR50F-xx-01/02 |
| HRC form | collaborative |
| Cable management | internal |
| Type of drive | electrical |
| Integrated position sensing | Analog 0 to 10 V |
| Stroke per jaw [mm] | 10 |
| Gripping force safety device | mechanical |
| Gripping force in closing (adjustable) max. [N] | 190 |
| Gripping force in opening (adjustable) max. [N] | 190 |
| Gripping force in accordance with ISO/TS 15066 [N] | <140 |
| Closing time [s] | 0.19 |
| Opening time [s] | 0.19 |
| Control time [s] | 0.03 |
| Dead weight of mounted gripper finger max. [kg] | 0.1 |
| Length of the gripper fingers max. [mm] | 80 |
| Repetition accuracy +/- [mm] | 0.05 |
| Voltage [V] | 24 |
| Current consumption max. [A] | 1 |
| Minimum positioning path per jaw [mm] | 0.5 |



RECOMMENDED ACCESSORY STORAGE STATION



NJ5-E2SK-01 Inductive Proximity Switch Cable 0,3 m - Connector M8

