## 2-JAW PARALLEL GRIPPERS SERIES GPP5000

## PRODUCT ADVANTAGES



## "The best"

## Steel Linear Guide The superior guidance system concept

The steel / steel guide stands for lasting precision, durability and a long service life-featuring maintenance intervals of up to 30 million gripping cycles. Benefit from these features and increase the profitability and process reliability of your machine.

## - Leakproof and corrosion protected - The universal gripper

Suitable for virtually all ambient conditions, with a sealed guide up to IP67 and corrosion protection as standard, you are able to use this gripper universally. As a result, the range of models in your production is reduced, along with a reduction in associated storage and process costs.

## - Aluminum Linear Guide - The alternative

Reduced to those aspects which are the most important, the steel / aluminum guide variant offers significantly better performance when compared to a similar gripper with a T-groove travel guide, and is on par with the best principles of toothed guidance systems.

## BENEFITS IN DETAIL


(1) Wedge hook mechanism

- Supports to absorb high forces and moments
- Synchronized gripper jaw movement

Gripper jaw

- Gripper fingers mounted using removable centering sleeves
- Lubricated for life via incorporated lubrication slotsSteel Linear Guide
- Steel in steel guide
- Enables use of extremely long gripper fingers
- Also available in steel / aluminum variant
(4) Mounting block
- mounting for inductive proximity switchIntegrated gripping force safety device
- Spring built into cylinder chamber as an energy store
(6) Drive
- Double-acting pneumatic rotor cylinderMounting and positioning
- Alternatively, on several sides for customized mounting
- Pneumatic and electrical versions identical apart from heightSensing slot
- mounting and positioning of magnetic field sensors
(9) Dual lip seal
- IP64 and up to IP67 (with purged air) for Protector version
- Prevents grease from being squeezed out, increasing service life


## SERIES CHARACTERISTICS

| Installation size |  | Variants |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | GPP50XX | -00 | -20 | -21 | -24 | -AL |
| N | Long stroke | $\bullet$ | - | $\bullet$ | $\bullet$ | - |
| NC | Long stroke / Spring closing | $\bullet$ | - | - | - | - |
| NO | Long stroke / Spring opening | $\bullet$ | $\bullet$ | - | $\bullet$ | - |
| S | High-strength | $\bullet$ | - | - | - |  |
| Sc | High-strength / Spring closing | - | - | - | - |  |
| so | High-strength / Spring opening | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |  |
| $\square$ | Steel Linear Guide | $\bullet$ | - | $\bullet$ | $\bullet$ |  |
| 5 | Aluminum Linear Guide |  |  |  |  | - |
|  | 15 million maintenance-free cycles (max.) |  |  |  |  | - |
| $3$ | 30 million maintenance-free cycles (max.) | - | - | - | - |  |
| + 200 | Inductive sensor | $\bullet$ | - | - | - |  |
| $+\frac{\mathrm{C}}{\square}$ | Magnetic field sensor | - | - | $\bullet$ | - | - |
| $\checkmark$ | Protected against corrosion | - | - | - | $\bullet$ |  |
|  | Purged air | $\bullet$ | - | - | - | - |
| $\pm$+ <br> $\square$ <br> $\square$ | Temperature-resistant |  | - |  | - |  |
|  | Clean room certified | $\bullet$ |  | - |  | - |
| IP 40 | IP40 |  |  |  |  | - |
| IP 64 | IP64 | $\bullet$ | $\bullet$ |  |  |  |
| IP 67 | IP67* |  |  | $\bullet$ | - |  |

* with purged air (max. 0,5 bar)


## TECHNICAL DATA

|  | Stroke per jaw | Gripping force |  | IP class |
| :---: | :---: | :---: | :---: | :---: |
| Installation size | [mm] | [ N ] | [kg] |  |
| GPP5003 | 2,5 | 140-205 | 0,08-0,12 | IP40 / IP64 / IP67* |
| GPP5004 | 2-4 | 200-630 | 0,15-0,3 | IP40 / IP64 / IP67* |
| GPP5006 | 3-6 | 330-1080 | 0,28-0,44 | IP40 / IP64 / IP67* |
| GPP5008 | 4-8 | 520-1670 | 0,53-0,76 | IP40 / IP64 / IP67* |
| GPP5010 | 5-10 | 885-2890 | 0,85-1,31 | IP40 / IP64 / IP67* |
| GPP5013 | 6-13 | 1410-4400 | 1,5-2,26 | IP40 / IP64 / IP67* |
| GPP5016 | 8-16 | 2090-6600 | 2,9-4,4 | IP40 / IP64 / IP67* |
| GPP5025 | 14-25 | 3280-9130 | 6,1-8,75 | IP64 / IP67* |
| GPP5030 | 17-30 | 5000-13550 | 9,2-13,7 | IP64 / IP67* |
| GPP5035 | 20-35 | 6100-15900 | 15,8-23,3 | IP64 / IP67* |
| GPP5045 | 26-45 | 10200-26950 | 33-50 | IP64 / IP67* |

## 2-JAW PARALLEL GRIPPERS INSTALLATION SIZE GPP5008

## PRODUCT SPECIFICATIONS

## -00-A / -20-A / -21-A / -24-A

Steel / steel guide

## - Gripping force diagram

[N] Shows the arithmetic total of the individual forces that occur on the gripper fingers, depending on the gripper finger length


## - Forces and moments

Displays static forces and moments that can also have an effect, besides the gripping force.


| $\mathrm{Mr}[\mathrm{Nm}]$ | 60 |
| :--- | :---: | :---: |
| $\mathrm{Mx[Nm}]$ |  |
| $\mathrm{My}[\mathrm{Nm}]$ | 105 |
| $\mathrm{Fa}[\mathrm{N}]$ | 65 |


| -AL-A |
| :---: |
| Steel / aluminum guide |

## Gripping force diagram

[N] Shows the arithmetic total of the individual forces that occur on the gripper fingers, depending on the gripper finger length


## - Forces and moments

Displays static forces and moments that can also have an effect, besides the gripping force.


| $\mathrm{Mr}[\mathrm{Nm}]$ | 55 |
| :--- | :---: | :---: |
| $\mathrm{Mx}[\mathrm{Nm}]$ | 95 |
| $\mathrm{My}[\mathrm{Nm}]$ | 60 |
| $\mathrm{Fa}[\mathrm{N}]$ | 1800 |

## VARIANTS



## TECHNICAL DATA

|  | - Technical data |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Order no. | GPP5008N-00-A | GPP5008NC-00-A | GPP5008NO-00-A | GPP5008S-00-A | GPP5008SC-00-A | GPP5008SO-00-A |
| Stroke per jaw [mm] | 8 | 8 | 8 | 4 | 4 | 4 |
| Gripping force in closing [N] | 520 | 710 |  | 1150 | 1580 |  |
| Gripping force in opening [ N ] | 560 |  | 750 | 1240 |  | 1670 |
| Gripping force secured by spring min. [N] |  | 190 | 190 |  | 430 | 430 |
| Closing time [s] | 0.035 | 0.025 | 0.045 | 0.035 | 0.025 | 0.045 |
| Opening time [s] | 0.035 | 0.045 | 0.025 | 0.035 | 0.045 | 0.025 |
| Dead weight of mounted gripper finger max. [kg] | 0.7 | 0.7 | 0.7 | 0.7 | 0.7 | 0.7 |
| Length of the gripper fingers max. [mm] | 125 | 115 | 115 | 115 | 105 | 105 |
| Repetition accuracy +/- [mm] | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 |
| Operating pressure min. [bar] | 3 | 4 | 4 | 3 | 4 | 4 |
| Operating pressure max. [bar] | 8 | 7 | 7 | 8 | 7 | 7 |
| Nominal operating pressure [bar] | 6 | 6 | 6 | 6 | 6 | 6 |
| Operating temperature [ ${ }^{\circ} \mathrm{C}$ ] | $-10 \ldots+90$ | $-10 \ldots+90$ | $-10 \ldots+90$ | $-10 \ldots+90$ | -10 ... +90 | $-10 \ldots+90$ |
| Air volume per cycle [ $\mathrm{cm}^{3}$ ] | 22 | 43 | 43 | 22 | 43 | 43 |
| Clean room applications according to DIN EN ISO 14644-1 | 6 | 6 | 6 | 6 | 6 | 6 |
| Protection to IEC 60529 | IP64 | IP64 | IP64 | IP64 | IP64 | IP64 |
| Protected against corrosion | Yes | Yes | Yes | Yes | Yes | Yes |
| Weight [kg] | 0.53 | 0.63 | 0.62 | 0.55 | 0.65 | 0.64 |


| Order no. |
| :--- |
| Operating temperature $\left[{ }^{\circ} \mathrm{C}\right]$ |

## - Technical Data - High Temperature Version

|  | - Technical Data - Protector Version |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Order no. | GPP5008N-21-A | GPP5008NC-21-A | GPP5008NO-21-A | GPP5008S-21-A | GPP5008SC-21-A | GPP5008SO-21-A |
| Clean room applications according to DIN EN ISO 14644-1 | 5 | 5 | 5 | 5 | 5 | 5 |
| Protection to IEC 60529 | IP67* | IP67* | IP67* | IP67* | IP67* | IP67* |
| Weight [kg] | 0.65 | 0.75 | 0.74 | 0.67 | 0.77 | 0.76 |


|  | - Technical Data - High Temperature Protector Version |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Order no. | GPP5008N-24-A | GPP5008NC-24-A | GPP5008NO-24-A | GPP5008S-24-A | GPP5008SC-24-A | GPP5008SO-24A |
| Operating temperature $\left[{ }^{\circ} \mathrm{C}\right]$ | -10 ... +130 | -10 ... +130 | -10 ... +130 | -10 ... +130 | -10 ... +130 | -10 ... +130 |
| Protection to IEC 60529 | IP67* | IP67* | IP67* | IP67* | IP67* | IP67* |
| Weight [kg] | 0.65 | 0.75 | 0.74 | 0.67 | 0.77 | 0.76 |
| * with purged air (max. 0,5 bar) |  |  |  |  |  |  |
|  | - Technical data |  |  |  |  |  |
| Order no. | GPP5008N-AL-A | GPP5008NC-AL-A | GPP5008NO-AL-A |  |  |  |
| Dead weight of mounted gripper finger max. [kg] | 0.6 | 0.6 | 0.6 |  |  |  |
| Length of the gripper fingers max. [mm] | 110 | 105 | 105 |  |  |  |
| Clean room applications according to DIN EN ISO 14644-1 | 4 | 4 | 4 |  |  |  |
| Protection to IEC 60529 | IP40 | IP40 | IP40 |  |  |  |
| Protected against corrosion | No | No | No |  |  |  |
| Weight [kg] | 0.51 | 0.61 | 0.6 |  |  |  |

## 2-JAW PARALLEL GRIPPERS INSTALLATION SIZE GPP5008

## TECHNICAL DRAWINGS



## TECHNICAL DRAWINGS



N / NC / NO / S / SC / SO
-21-A / -24-A


Hoseless air feed-through M3

(1) Gripper attachment
(2) Energy supply
(3) Fixing for gripper finger
(6) Integrated slot for magnetic field sensor
(7) Mounting block (not for variant AL-A)
(19) Air purge connection option (max. 0,5 bar)
(35) Attachment option for customer-specific fittings
(38) Adapter
(39) Gripper
(44) Clamping sensor (not for variant AL-A)
(45) Switch cam adjustment (not for variant AL-A)
(A) Air connection (close)
(B) Air connection (open)
(A) Air connection, alternative (close)
(B) Air connection, alternative (open)

|  | Position 19 sealing air connection option |  |
| :--- | :--- | :--- |
| Order no. | $-\mathbf{0 0 - A} / \mathbf{- 2 0 - A} / \mathbf{- 2 1 - A} / \mathbf{- 2 4 - A}$ | -AL-A |
| $\mathrm{H}[\mathrm{mm}]$ | 42.8 | 55.7 |
| $\mathrm{~L}[\mathrm{~mm}]$ | 11 | 9 |
| $\mathrm{~h}[\mathrm{~mm}]$ | 24.8 | 37.7 |

## 2-JAW PARALLEL GRIPPERS INSTALLATION SIZE GPP5008

## ACCESORIES



INCLUDED IN DELIVERY


6 [piece]
Centering Disc

## RECOMMENDED ACCESSORIES




UB5008AL
Universal jaw aluminium


UB5008ST
Universal jaw steel


EB5008AL
Aluminum adjustment jaw


EB5008ST
Steel adjustment jaw


WB5008L
Changeable jaw, loose-part-set


WB5008F
Changeable jaw, fix-part

## ENERGY SUPPLY



WVM5
Angled Fittings - Quick
Connect Style


DSV1-8
Pressure safety valve


DSV1-8E
Pressure safety valve with quick exhaust

## SENSORS



## NJ4-E2SK-01

Inductive Proximity Switch Cable 0,3 m - Connector M8 *Not for variant AL-A


## MFS01-S-KHC-P1-PNP

 Magnetic field sensor angled, cable 0.3 m - M8 connector

## MFS02-S-KHC-P1-PNP

 Magnetic field sensor straight, cable 0.3 m - M8 connector

## MFS01-S-KHC-P2-PNP

 2-point sensor angled, cable 0.3 m - M8 connector

MFS02-S-KHC-P2-PNP 2-point sensor straight, cable $0.3 \mathrm{~m}-\mathrm{M} 8$ connector


MFS02-S-KHC-IL Position sensor straight, cable 0.3 m - connector M8

## 音蕴 <br> CONNECTIONS / OTHER



## KAG500

Plug-in connector Straight Cable 5m - Socket M8 (female)

## 2-JAW PARALLEL GRIPPERS SERIES GPP5000 FUNCTIONAL DESCRIPTION

## GRIPPING COMPONENTS



Universal jaws - UB5000
Can be used immediately or for individual reprocessing
The gripper blanks are available in aluminum (AL) and steel (ST) versions and are installed directly on the gripper using the screws in the scope of delivery. The fits for the centering sleeves are already in place for this purpose. One universal jaw is required for each gripper jaw.

## Adjustment jaws - EB5000

For tool-free adaptation of the gripper range
By manually activating the locking mechanism, which is pre-tensioned by a spring, the adjustment jaw can be moved within a grid of detent notches that has a number scale. Depending on the forces and torques that apply, the adjustment jaws are available in aluminum (AL) and steel (ST) versions. One adjustment jaw is required for each gripper jaw.

## Interchangeable jaws - WB5000

Enable fast change of individual gripper fingers
For each gripper jaw, a fixed part and at least one loose part set is needed, depending on the number of gripper fingers to be changed. Manual locking via the Torx wrench included in the scope of delivery of the fixed part can take place from two sides.


## Pneumatic threaded connections

Available in straight and angled design. Can be chosen freely depending on the space conditions or installation situation.


## Pressure safety valve - DSV

Ensures safe retention of force and position if the system pressure drops
The integrated double check valve, which can be unlocked, retains the system pressure of the gripper in case of EMERGENCY STOP. To ensure the function, the valve must be installed as close to the gripper's air connection as possible. In variant E, two pushbuttons are installed that allow for controlled bleeding of the gripper.

## 2-JAW PARALLEL GRIPPERS SERIES GPP5000 FUNCTIONAL DESCRIPTION

## E



Quick exhaust valve - DEV
For rapid bleeding of the compressed air and preventing back pressure
The inline valves make a faster cycle time possible and prevent the formation of condensate in grippers with a small cylinder volume. To ensure the function, the valve must be installed as close to the gripper's air connection as possible.


## Inductive sensors - NJ*

For direct position sensing of the gripper jaws
The sensor is guided into the intake as far as it will go and fixed in place using the lateral clamping screw. Tuning to the desired position then takes place by adjusting the cam switch. The sensors are available in versions with 5 m cables with exposed leads and $0,3 \mathrm{~m}$ cable with connector, as well as with direct plug orientation.
*Not for variant AL-A

## SENSORS

MFSO2


MFSO1


## 1-point magnetic field sensors - MFS

For non-contact sensing of the piston position
These sensors are installed in the C-groove of the gripper and detect the magnet attached to the piston of the gripper. To ensure use in a wide variety of space conditions, the sensors are available in two variants. While the horizontal MFS02, with straight cable outlet, disappears into the C-groove of the gripper almost completely, the vertical MFS01 is taller, but has a cable outlet that is offset at an angle of $90^{\circ}$. The variants are available in versions with 5 m cables with exposed leads and $0,3 \mathrm{~m}$ cable with connector.

## 2-JAW PARALLEL GRIPPERS SERIES GPP5000 FUNCTIONAL DESCRIPTION



SENSORS

MFSO2


## 2-point magnetic field sensors - MFS

With two freely programmable switching points
Using the programming unit integrated in the cable, two switch points can be freely defined for this sensor. To do so, the sensor is clamped in the C-groove, the gripper approaches position one and the position is taught in using the teach button. Afterwards, the second position is approached with the gripper and programmed. To ensure use in a wide variety of space conditions, the sensors are available in two variants. While the horizontal MFSO2, with straight cable outlet, disappears into the C-groove of the gripper almost completely, the vertical MFSO1 is taller, but has a cable outlet that is offset at an angle of $90^{\circ}$. The sensors are available in versions with 5 m cables with exposed leads and $0,3 \mathrm{~m}$ cable with connector.

## 를



## Plug-in connectors

For extending and fabricating the connection lines for the sensors
Cables with a length of 5 m with exposed leads are available. Depending on the specific needs, the cables can be shortened or fabricated with connectors in sizes M8 and M12.

## EONNECTIONS / OTHER



## Centering sleeves

For defined position measurement of the gripper fingers
The centering sleeves are inserted into the fits of the gripper jaws to define the position of the gripper fingers. The centering sleeves are comparable to a pin connection.

## 2-JAW PARALLEL GRIPPERS SERIES GPP5000 GRIPPER FINGER LENGTH

MAXIMUM GRIPPER FINGER LENGTH






## Example 1

Vertical force application point
a $=0 \mathrm{~mm}$
$b=200 \mathrm{~mm}$

## Example 2

Horizontal force application point
$a=200 \mathrm{~mm}$
$\mathrm{b}=0 \mathrm{~mm}$

## Example 3

Maximum permissible projection
$a=120 \mathrm{~mm}$
$b=160 \mathrm{~mm}$

The examples show the maximum horizontal (a) and vertical (b) gripper finger length using the example of a GPP5013N-00-A, which is represented by the blue area.

## GRIPPING FORCE AS A FUNCTION OF GRIPPER FINGER LENGTH



- Gripping force diagram

Shows the arithmetic total of the individual forces that occur on the gripper
[ N$]$ fingers, depending on the gripper finger length


## Example 4

Resulting gripper finger length for determining the gripping force
$\mathrm{a}=55 \mathrm{~mm}$
$\mathrm{~b}=58 \mathrm{~mm}$
$x=\sqrt{55^{2}+58^{2}}=80 \Rightarrow 2125 \mathrm{~N}$

## GUIDE CHARACTERISTICS

## Steel / aluminum guide and steel / steel guide in comparison

In general, the maximum possible length of gripper fingers of a steel / aluminum guide is lower in comparison to the steel / steel guide, due to the lower yield point of aluminum. While the maximum gripper finger length in the horizontal (a) and vertical (b) direction can be fully utilized for the steel / steel guide, the maximum gripper finger length that is specified in the technical data for the steel / aluminum guide is reduced by $20 \%$ at a horizontal (a) projection. The lower efficiency of a steel / aluminum guide also leads to a higher decrease in gripping force at an increased gripping finger length and to a reduction in service life as a result of a lower resistance to wear.

## Steel / aluminum guide

Steel / aluminum guides are very common worldwide. They are available in many different forms and are installed in virtually all commercially available grippers from an extremely wide variety of manufacturers. The steel / aluminum grippers from Zimmer Group are available as AL variants of the tried-and-tested 5000 Series. Their designs are geared toward the important aspects and they are very cost-effective.

## Steel / steel guide

Steel / steel guides are the best and first choice wherever durability and robustness are essential. The Steel Linear Guide from Zimmer Group is also clearly distinguished from a steel / aluminum guide thanks to its exclusive design featuring higher material characteristics.

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Steel Linear Guide - Added value in detail
+ Steel in steel guide
+ IP64 and up to IP67 (with sealing air) in the protector version
+ Corrosion protected
+ Up to 30 million maintenance-free cycles (max.)
```

